

Figure 1: Example of a Laplacian filter  $(G(\theta) = |\theta|^2)$  design. The designed filter (a) is comprised of the frequency squared response (for  $\theta \leq \frac{3}{4}\pi$ ) and the complementary response ( $\theta > \frac{3}{4}\pi$ ), to satisfy the symmetry condition ( $G(\pi) = 0$ ). The discrepancy between the designed and desired responses is caused by the small filter order. The resulting filter (b) is similar to the Laplacian used in [1] (dashed red).

## SUPPLEMENTARY: WHITENING FILTER DESIGN

In [1], a 9-tap square root of a Laplacian filter is used to whiten the signal. This Laplacian has an approximated frequency response squared proportional to  $|\omega|^2$  for a 1D frequency  $\omega$ . It is therefore suitable as a model of natural images  $(|\omega|^{-2})$ . In our case, we estimate the exponent as a floating-point number and therefore require a more refined method of whitening filter design.

The desired response of the filter is designed as follows. Given  $\alpha$ , an estimated exponent, the whitening filter is

$$G\left(\omega\right) = \left|\omega\right|^{\alpha/2}.\tag{1}$$

This is due to the fact that

$$x_2 = x_1 * h \Rightarrow S_{X_2}(\omega) = S_{X_1}(\omega) |G(\omega)|^2,$$

and to perform whitening of  $x_1$  with  $P_{X_1}(\omega) \propto \omega^{-\alpha}$ , the filter itself should have a frequency response with an exponent  $\alpha/2$ . There exist several alternatives for designing such a filter. We choose the filter to be as similar as possible to a Laplacian, specifically: anti-symmetrical, with compact support and odd-valued. We thus choose a Type III linear-phase FIR filter.

To create a Type III filter, its periodicity should be taken into account; it should satisfy  $G(0) = G(\pi) = 0$ . Therefore, instead of using (1) directly, we design the desired response for the range  $\theta_1 \in [0, \frac{3}{4}\pi]$  and complete the response in the range  $\theta_2 \in (\frac{3}{4}\pi, \pi)$  via a first order polynomial,  $p(\theta)$  so that the response is continuous and  $G(\pi) = 0$ . The filter is then designed with the same length as in [1] (9-tap) with standard least-squares FIR filter design methods. We note that using Type III FIR filters we can reconstruct almost exactly the Laplacian filter used in [1] when designing a filter with desired exponent  $\alpha = 2$  (Fig. 1).

## REFERENCES

[1] Amit Goldstein and Raanan Fattal. Blur-kernel estimation from spectral irregularities. In Eur. Conf. Comput. Vis., pages 622-635. Springer Berlin Heidelberg, oct 2012.